

# Two Computational Paradigms for Big Data

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# Outline of the lecture

## Motivation

- **Data Stream** model
- **MapReduce** model

**Goal:** To give an idea of the algorithmic techniques in massive data

## For each model

- Description
- Canonical examples
- Sample algorithms

Will not cover the full list

# Motivation

- Big data (Tb++)
  - Data grows faster than CPU speed
  - Web, social, satellite, genome, sensor, ...
- Efficient algorithms
  - Linear time is the only feasible option
  - Data can be distributed across machines/racks
- Small memory footprint
  - Cannot hold the data or even portions of it in main memory
- Approximate answers suffice
  - An exact answer is not worth going after



**How to model efficient computation on massive data?**

# Sample questions

- How many **unique** web search queries were issued yesterday?
- How many shopping sites were **clicked together** in a user web search session?
- What were the **top** queries (by volume) last week?
- Which is the **densest** community in a social network?
- Which web sites have **similar** usage patterns?
- How many “**friend-of-a-friend is a friend**” instances are in a social network?

# CPU vs Memory

**Polynomial**

**Sublinear**

**Single**

RAM

Data streams  
Sketches

**Multiple**

PRAM

MapReduce  
Distributed streams  
Distributed sketches

	<b>Polynomial</b>	<b>Sublinear</b>
<b>Single</b>	RAM	Data streams Sketches
<b>Multiple</b>	PRAM	MapReduce Distributed streams Distributed sketches

# CPU vs Input

**Batch**

**Online**

**Single**

RAM

Data streams

**Multiple**

MapReduce

Distributed streams

	<b>Batch</b>	<b>Online</b>
<b>Single</b>	RAM	Data streams
<b>Multiple</b>	MapReduce	Distributed streams

# I. Data Stream Model

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# Data Streams: Outline

- Model description and characteristics
- Statistical problems
  - Distinct elements
  - Frequency moments
  - Frequent elements
- Graph applications
  - Triangle counting
  - Densest subgraph

# DS: Characteristics

- Data arrives in a **stream**
  - No random access to data
  - Can be new data or updates to existing data
- Typically single CPU
- Very **limited** amount of memory
  - Some cases, only Mb even for Tb+ data
  - Cannot store any non-trivial portion of the data in memory
  - Data size may be infinite/unknown in advance
- Ideally, make a **single pass** over the data
  - In some cases, can make multiple passes

# DS: Practical applications

- **Web mining**
  - How many unique queries were processed by the search engine in the last two days?
  - What are the most frequent queries in the past hour?
  - Find dense communities in a social network
- **Databases**
  - Query selectivity, join size estimation
  - Query planning and execution
- **Networks**
  - Sensor/satellite data
  - Traffic and packet monitoring

# Basic DS model



Compute a **function** of inputs  $X = x_1, \dots, x_n$

- Ideally use  $O(\log^c n)$  memory
- Small processing time per element
- Approximate solutions are sufficient
- Can use randomness (many cases, needed)
- Make one or few passes over the data

# DS: Algorithmic philosophy

- Find **how to represent** the input
  - Sufficient for the function to be approximated
  - Small enough to be space-efficient
- **Update** the stored representation upon seeing another input
  - Efficient and incremental updates
- **Tools** at disposal
  - Randomization
  - Hashing
  - Sketching

# DS Warmup: Missing number

Given an arbitrary permutation of  $[n]$  with one number missing, find the missing number

Input.  $\pi_1, \dots, \pi_{n-1}$  (Eg,  $n = 5$ , input = 3 4 1 5)

Algorithm.  $S = \sum_{i=1, n-1} \pi_i$

**Output  $n(n+1)/2 - S$**

Memory used =  $O(\log n)$  bits

Can extend this to two numbers missing and so on

# DS Warmup: Reservoir sampling

Given an infinite stream, maintain a uniform random sample from the stream (seen so far)

Input.  $x_1, x_2, \dots$

Algorithm.  $S = x_1$

for each  $i$ :

$S = x_i$  with probability  $1/i$

**Lemma.**  $S$  is a uniform random sample at any point

**Proof.** Fix  $i$ . At any time  $t \geq i$ ,

$$\Pr [x_i = S] = (1/i) \cdot i/(i+1) \cdot (i+1)/(i+2) \cdots = 1/t$$

# $F_0$ : Counting distinct elements

Given  $X = x_1, \dots, x_n$  compute  $F_0(X)$ , the **number of distinct elements** in  $X$

**Motivation.** Number of unique web queries

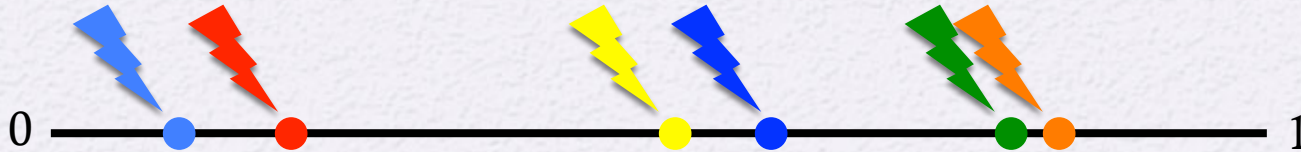
**Example.**  $X = 3\ 3\ 2\ 4\ 5\ 2\ 7\ 2\ 3$ ;  $F_0(X) = 5$

**$(\epsilon, \delta)$ -approximation.** Output  $F_0'(X)$  such that with probability  $1 - \delta$ ,  $F_0'(X) = (1 \pm \epsilon) F_0(X)$

- Assume  $x_i \in [m]$  and  $\log m = O(\log n)$ ; else hash input
- Sampling needs lots of space
- Without randomization/approximation, this is hard

# $F_0$ : Intuition

Suppose  $h:[m] \rightarrow (0, 1)$  is truly random



Then  $\min \{ h(x_i) \}$  is roughly  $\sim 1/F_0(X)$

Reciprocal of this value is  $F_0(X)$

More robust: Keep the  $t$ -th smallest value  $v_t$

$v_t$  is roughly  $\sim t/F_0$

A good estimator of  $F_0$  is  $t/v_t$

# $F_0$ : Algorithm

$t = 1/\epsilon^2$ ;  $h:[m] \rightarrow [m^3]$ ,  
pairwise independent

$T = \emptyset$

for  $i = 1, \dots, n$ :

$T \leftarrow t$  smallest values in  
 $T \cup h(x_i)$

$v_t = t$ -th smallest value in  $T$

Output  $tm^3/v_t$

- **Space:**  $O(\log m)$  for  $h$  and  $O(1/\epsilon^2 \cdot \log m)$  for  $T$
- **Time:** Balanced binary search tree for  $T$

Compute many estimators independently and output their median

- To achieve confidence  $1-\delta$

**Theorem.**  $F_0'(X)$  is an  $(\epsilon, \delta)$ -approximation

# $F_2$ : Second frequency moment

- $f_j$  = frequency of  $j$  =  $\#\{j \text{ occurs in } X\}$

Given  $X = x_1, \dots, x_n$  compute  $F_2(X) = \sum_{j=1..m} f_j^2$

Motivation. Self-join size estimation

Example.  $X = 3\ 3\ 2\ 4\ 5\ 2\ 7\ 2\ 3$ ;  $f_2 = f_3 = 3$ ,  $f_4 = f_5 = f_7 = 1$

$$F_2(X) = 3^2 + 3^2 + 1^2 + 1^2 + 1^2 = 21$$

$(\epsilon, \delta)$ -approximation. W.p.  $1 - \delta$ ,  $F_2'(X) = (1 \pm \epsilon) F_2(X)$

- Sampling needs lots of space
- Without randomization/approximation, this is hard

# F<sub>2</sub>: Algorithm

$$\mathbf{h}: [m] \rightarrow \{ +1, -1 \}$$

Random projection of the frequency vector

$$\mathbf{Z} = \sum_{i=1..n} \mathbf{h}(\mathbf{x}_i)$$

$$\mathbf{Z} = \sum_{i=1..n} \mathbf{h}(\mathbf{x}_i) = \sum_{j=1..m} f_j \mathbf{h}(j)$$

Output  $\mathbf{Z}^2$

$$\begin{pmatrix} -1 & +1 & -1 & -1 \end{pmatrix} \begin{pmatrix} f_1 \\ f_2 \\ f_3 \\ f_4 \end{pmatrix}$$

# $F_2$ : Analysis

- $h:[m] \rightarrow \{ +1, -1 \}$ ;  $E[h(j)] = 0$

**Lemma.**  $E[Z^2] = F_2$

**Proof.**  $Z = \sum_{i=1..n} h(x_i) = \sum_{j=1..m} f_j h(j)$

$$\begin{aligned} E[Z^2] &= E[ \sum_{j, j'=1..m} f_j h(j) \cdot f_{j'} h(j') ] \\ &= E[ \sum_{j \neq j'} f_j h(j) \cdot f_{j'} h(j') ] + \sum_{j=1..m} f_j^2 \\ &= 0 + \sum_{j=1..m} f_j^2 = F_2 \end{aligned}$$

**Lemma.**  $\text{Var}[Z^2] \leq 2F_2^2$

# $F_2$ : Analysis

Compute estimators  $Z_1, \dots, Z_k$  independently and output **average**  $Y = \sum Z_i^2/k$  where  $k = 1/\epsilon^2$

- This reduces the **variance**

Compute estimators  $Y_1, \dots, Y_1$  independently and output **median**  $\{ Y_i \}$

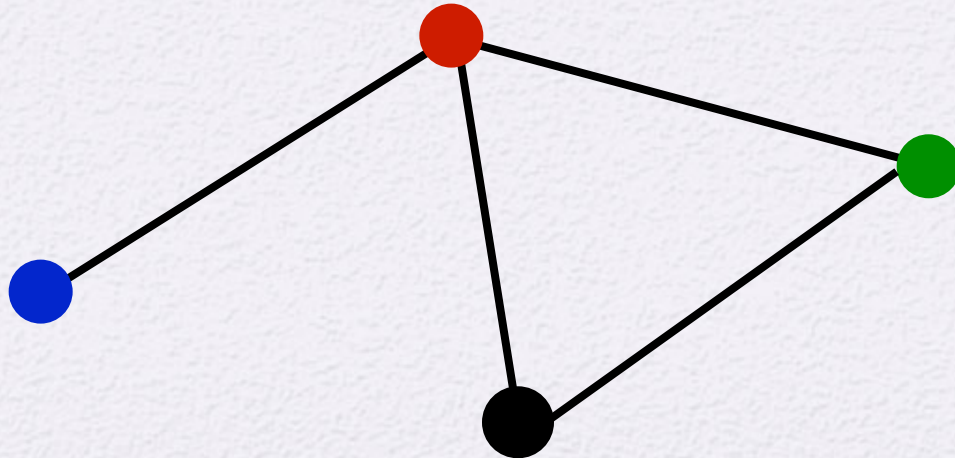
- To achieve **confidence**  $1-\delta$
- **Space**:  $O(1/\epsilon^2 \cdot \log 1/\delta \cdot \log m)$ ; one pass

**Theorem.**  $F_2'(X)$  is an  $(\epsilon, \delta)$ -approximation

# Application: Triangle counting

Given an undirected graph, count the **number of triangles**

Motivation. Social network analysis



# Triangle counting (contd)

For edge  $(u, v)$ , float virtual triples  $\langle u, v, w \rangle$  for  $w \neq u, v$

Compute  $F_0, F_1, F_2$  of this virtual stream

$T_i = \#$  triples with **exactly  $i$  edges** among them



$$T_0 + T_1 + T_2 + T_3 = \binom{n}{3}$$

$$F_0 = T_1 + T_2 + T_3$$

$$F_1 = \sum_{u,v,w} i \cdot T_i$$

$$= m(n-2)$$

$$F_2 = \sum_{u,v,w} i \cdot T_i^2$$

$$= T_1 + 4 T_2 + 9 T_3$$

Estimate  $F_0, F_2$  and use that to estimate  $T_3$

# CountMin: Frequent elements

- Given  $X = x_1, \dots, x_n$ , **additively approximate**  $f_j$ 
  - We focus on high-frequency counts
- Motivation: Most **frequent** web queries
- **Main idea:** use a hash function to count the number of occurrences of an element
  - Use multiple hash functions to mitigate collisions

# CM: Algorithm

$h_i: [m] \rightarrow [w], w = 1/\epsilon$

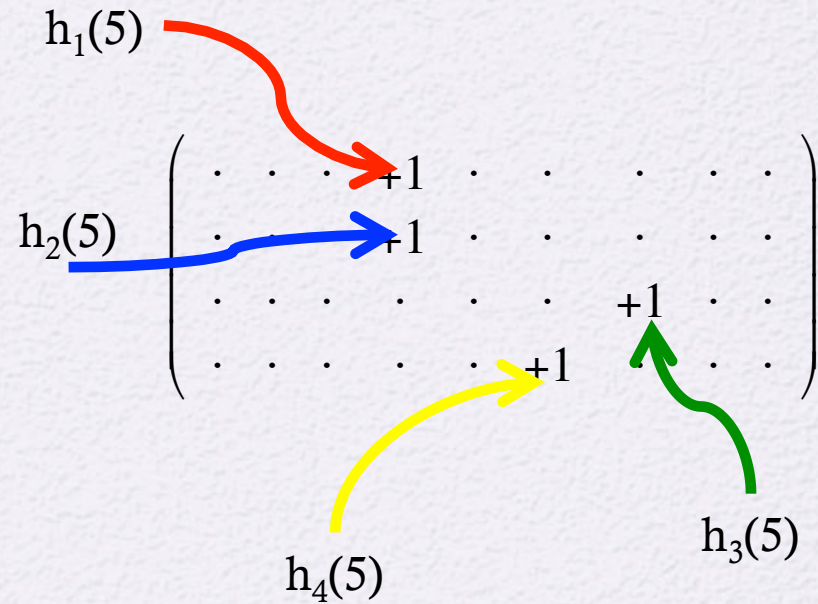
for  $i = 1, \dots, n$ :

for  $d = 1, \dots, \log 1/\delta$ :

$\text{count}[d, h_d(x_i)]++$

**Output**

$f_j' = \min_d \{ \text{count}[d, h_d(j)] \}$



# CM: Analysis

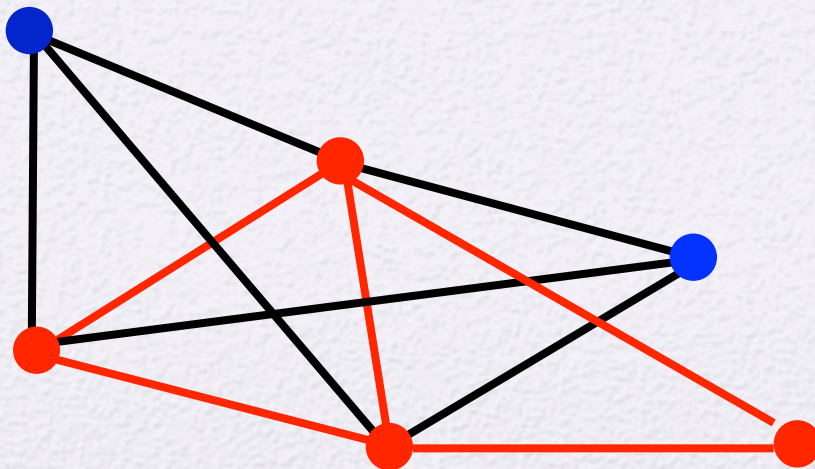
**Lemma.**  $f_j' \geq f_j$  and  $f_j' \leq f_j + \epsilon |f|$  with probability  $1 - \delta$

**Proof.**

- Count is always overestimated
  - Hashes can collide
- Chance the minimum count is way off is low
  - From Markov's inequality

# Densest subgraph

- Find the **densest subgraph** in a undirected graph
  - **Density** of a subgraph is the ratio of the number of edges to the number of nodes
  - Motivation. **Community** finding
  - **c-approximation** = when density is at most c times worse then the best density



$$\text{Density}(\bullet) = 5/4 = 1.2$$

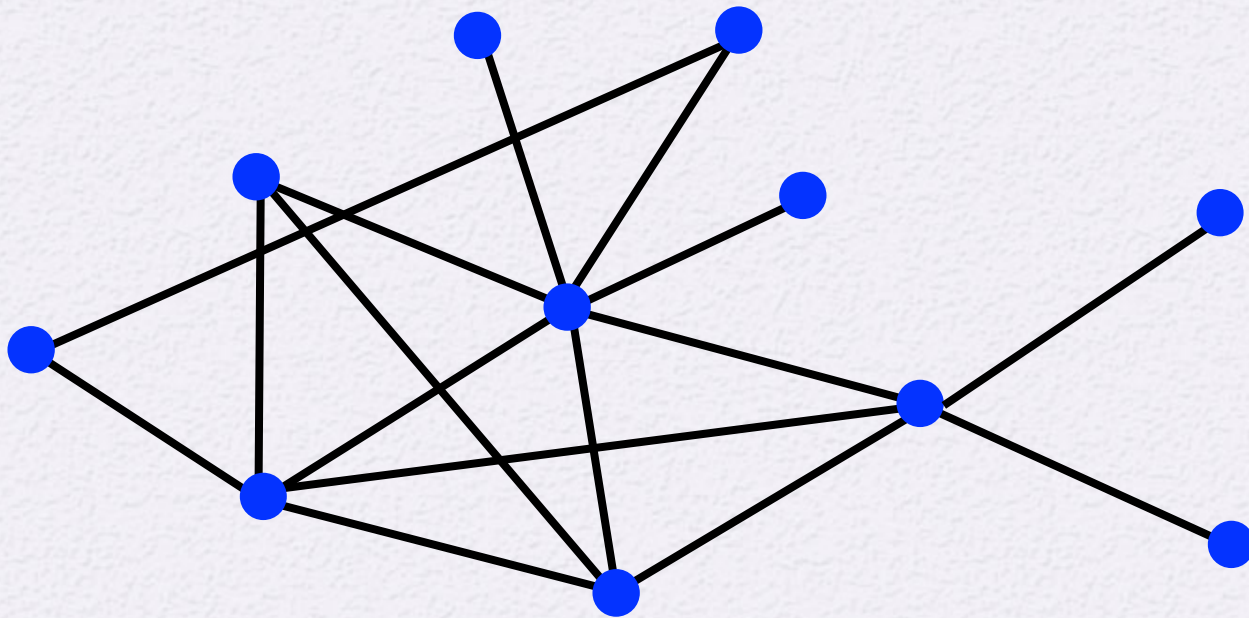
# DSG: Algorithm

A simple iterative algorithm

- **Compute the average degree**
- **Delete all nodes whose degree is below the average**
- **Keep track of the density at each step**

**Output the densest graph seen during the iteration**

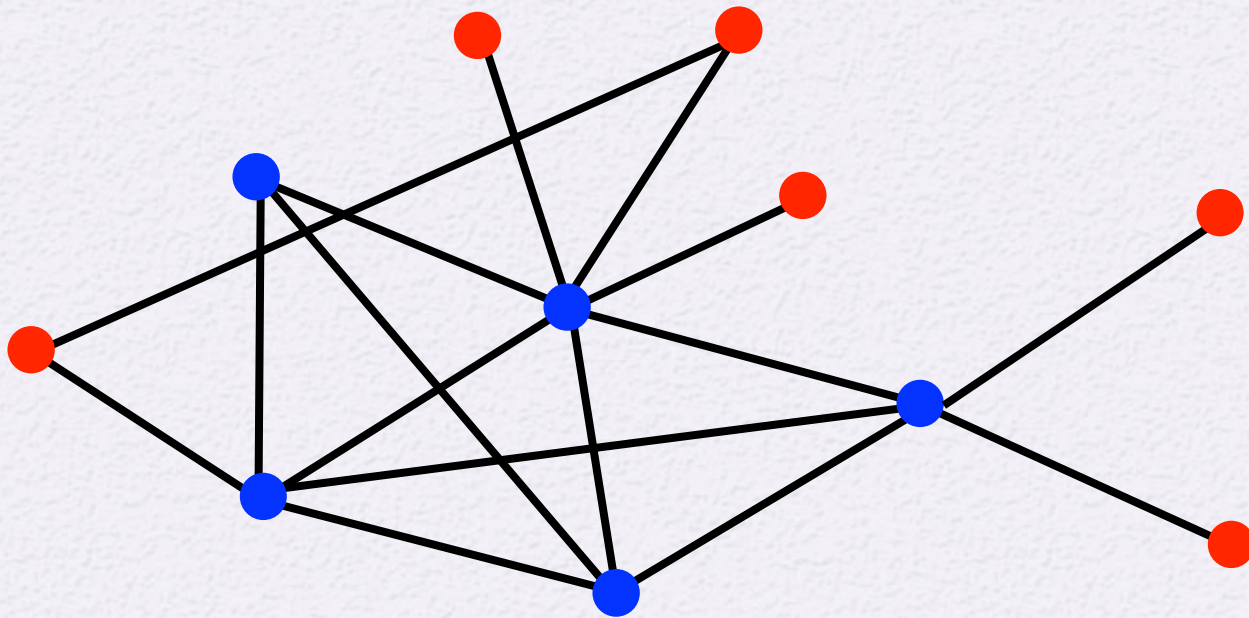
# DSG: Example



density =  $16/11 = 1.45$ ; average degree =  $2 * \text{density} = 2.90$

**Best density = 1.45**

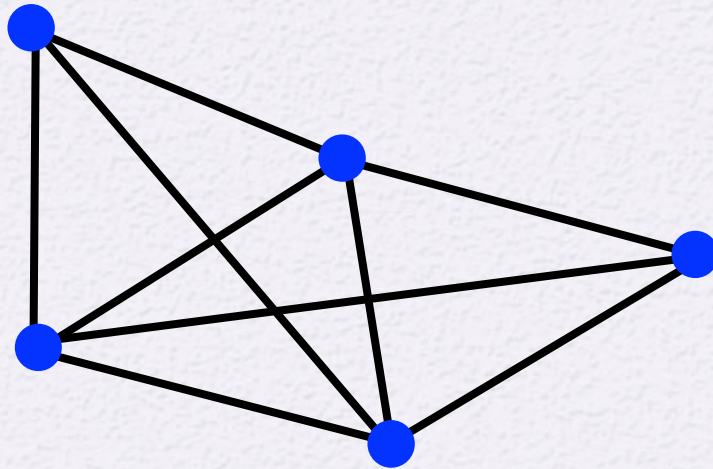
# DSG: Example (contd)



density =  $16/11 = 1.45$ ; average degree =  $2 * \text{density} = 2.90$

Best density = 1.45

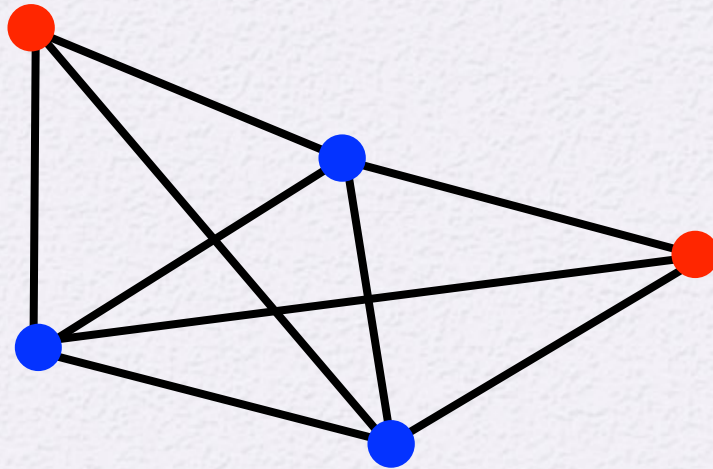
# DSG: Example (contd)



density =  $9/5 = 1.8$ ; average degree =  $2 * \text{density} = 3.6$

**Best density = 1.8**

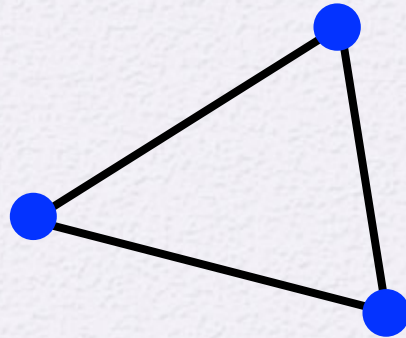
# DSG: Example (contd)



density =  $9/5 = 1.8$ ; average degree =  $2 * \text{density} = 3.6$

**Best density = 1.8**

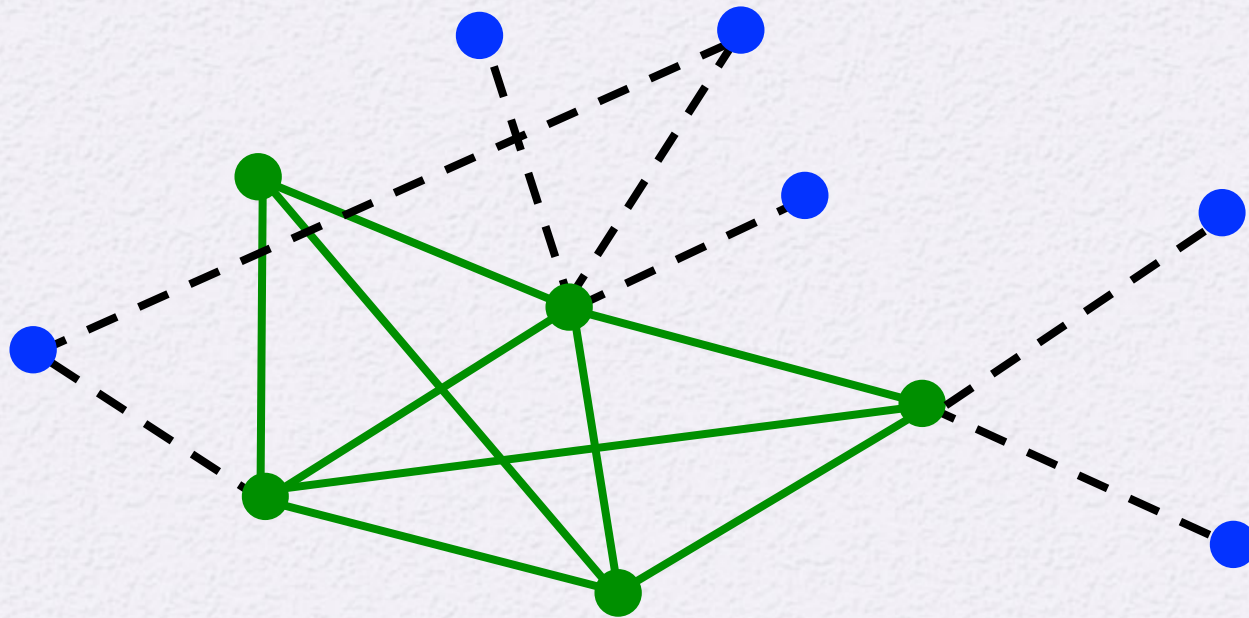
# DSG: Example (contd)



density =  $3/3 = 1$ ; average degree =  $2 * \text{density} = 2$

**Best density = 1.8**

# DSG: Example (contd)



Best density = 1.8

# DSG: Quality

**Theorem.** The output is a  $(2+\epsilon)$ -approximation  
**Proof.**

- $V^*$  = **optimal** subgraph,  $\rho^*$  = **optimal density**
- Each degree in  $V^*$  is **at least**  $\rho^*$ 
  - Otherwise can improve the optimum
- Assume you only remove the lowest degree node and consider the first subgraph  $V'$  when you are about to remove a node in  $V^*$ 
  - In reality, remove all nodes with degree  $\leq (1+\epsilon)$  average degree
- Density of  $V' \geq |\rho^* V'/2| / |V'| = \rho^*/2$

# DSG: Efficiency

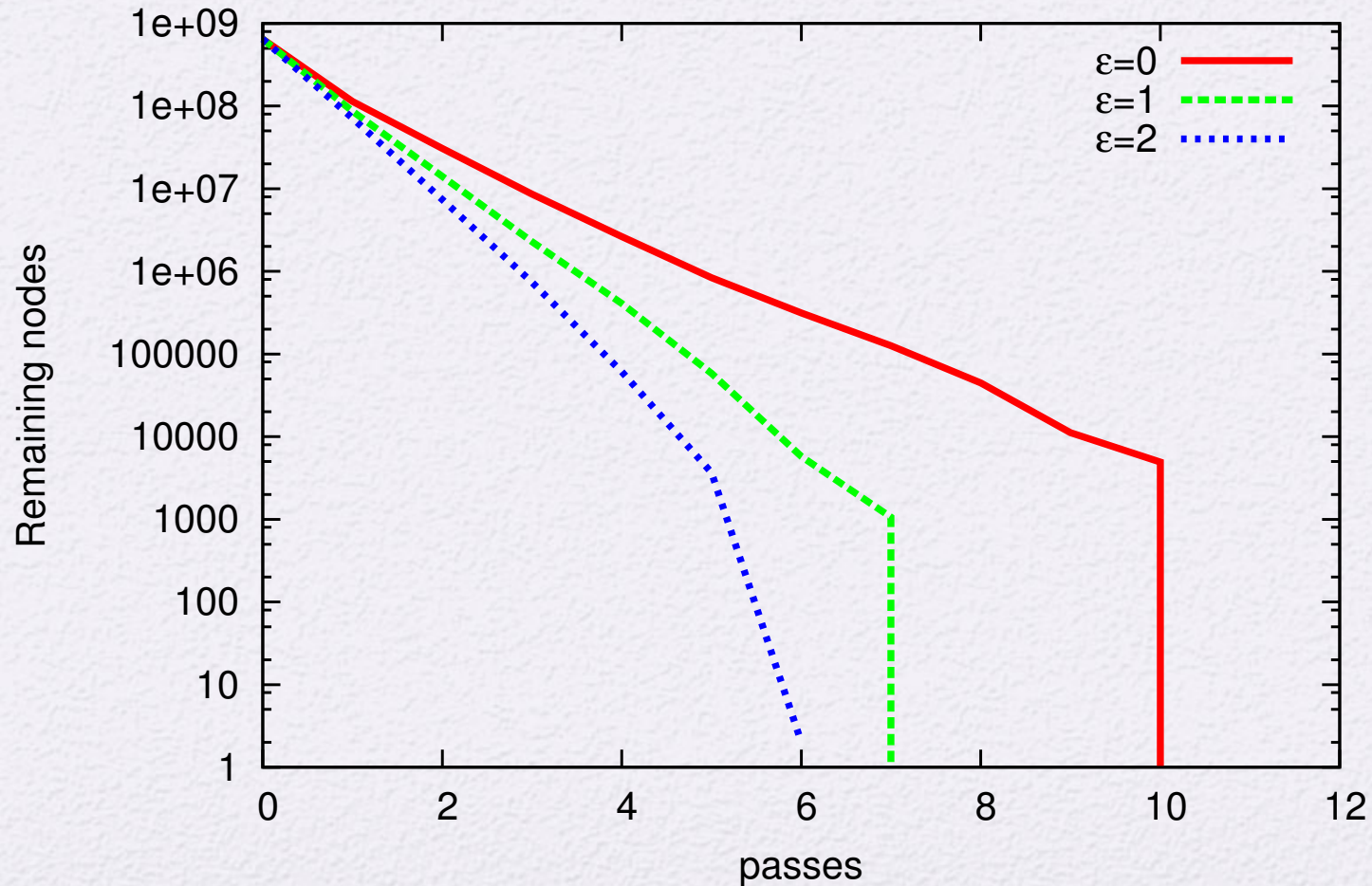
**Theorem.** The algorithm makes  $O(\log_{1+\epsilon} n)$  passes and uses  $O(n)$  memory

**Proof.**

- One **cannot** have too many nodes above average
- At most most  $1/(1+\epsilon)$  fraction of nodes **survive** each pass
- Hence the algorithm terminates after  **$\log_{1+\epsilon} n$  passes**

# DSG: Performance

IM: Remaining graph vs passes



# DS: Some references

- N. Alon, Y. Matias, M. Szegedy. The space complexity of approximating the frequency moments, JCSS 1999
- S. Muthukrishnan. Data Streams: Algorithms and Applications, Now Pub., 2005
- Z. Bar-Yossef, R. Kumar, D. Sivakumar. Reductions in streaming algorithms, with an application to counting triangles in graphs, SODA 2002
- G. Cormode and S. Muthukrishnan. An improved data stream summary: The Count-Min sketch and its applications, LATIN 2004
- B. Bahmani, R. Kumar, S. Vassilvitskii. Densest subgraphs in streaming and MapReduce. VLDB 2012

# II. MapReduce Model

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# MapReduce: Outline

- Model description and characteristics
- Graph applications
  - Connected components
  - Counting triangles
  - Maximal matching
- Clustering application
  - K-means

# MR: Characteristics

- **Multiple** CPUs
  - 10s to 10,000s processors
- **Sub-linear** memory
  - Few Gb of memory per machine, even for Tb+ sized data
  - Memory is **not shared** (unlike PRAM)
- **Batch processing**
  - Data processed in **multiple rounds**
  - Extensions used for incremental updates, online algorithms

# MR: Practical applications

- MR used very widely for large data analysis
  - Industry: Google, Yahoo, Amazon, Facebook, Netflix, LinkedIn, New York Times, eHarmony, ...
  - Adopted by the academic community as well
- Open source versions available
  - Hadoop and its extensions
- Many abstractions on top of MR
  - Pregel, Hive, Pig, ...
  - Same computational model underneath

# Basic MR model

Computation consists of one or more rounds of Map and Reduce steps

The input is partitioned across different machines

- **Map step (mapper)**

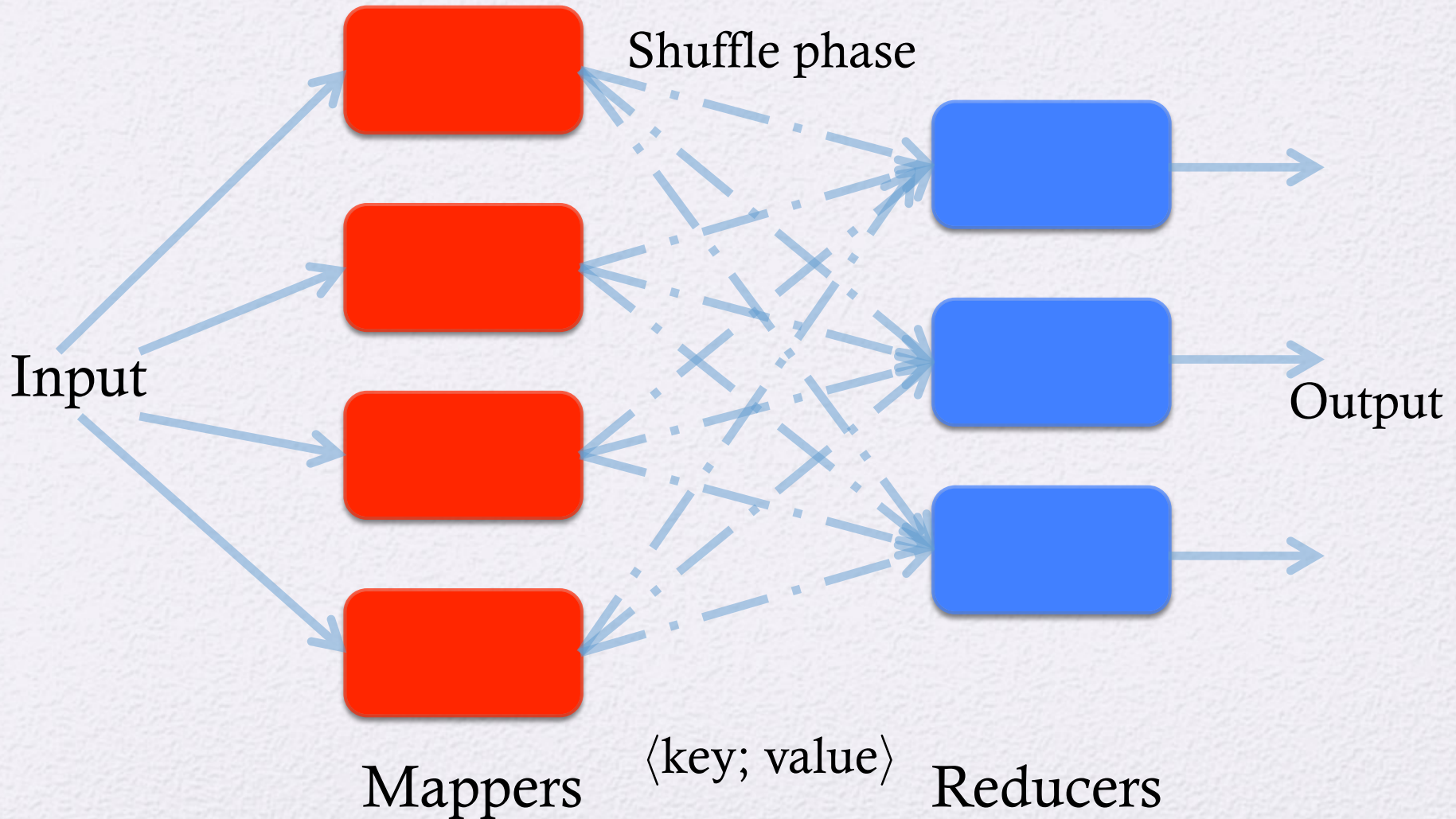
Each mapper processes its input and emits **⟨key; value⟩**

- **Reduce step (reducer)**

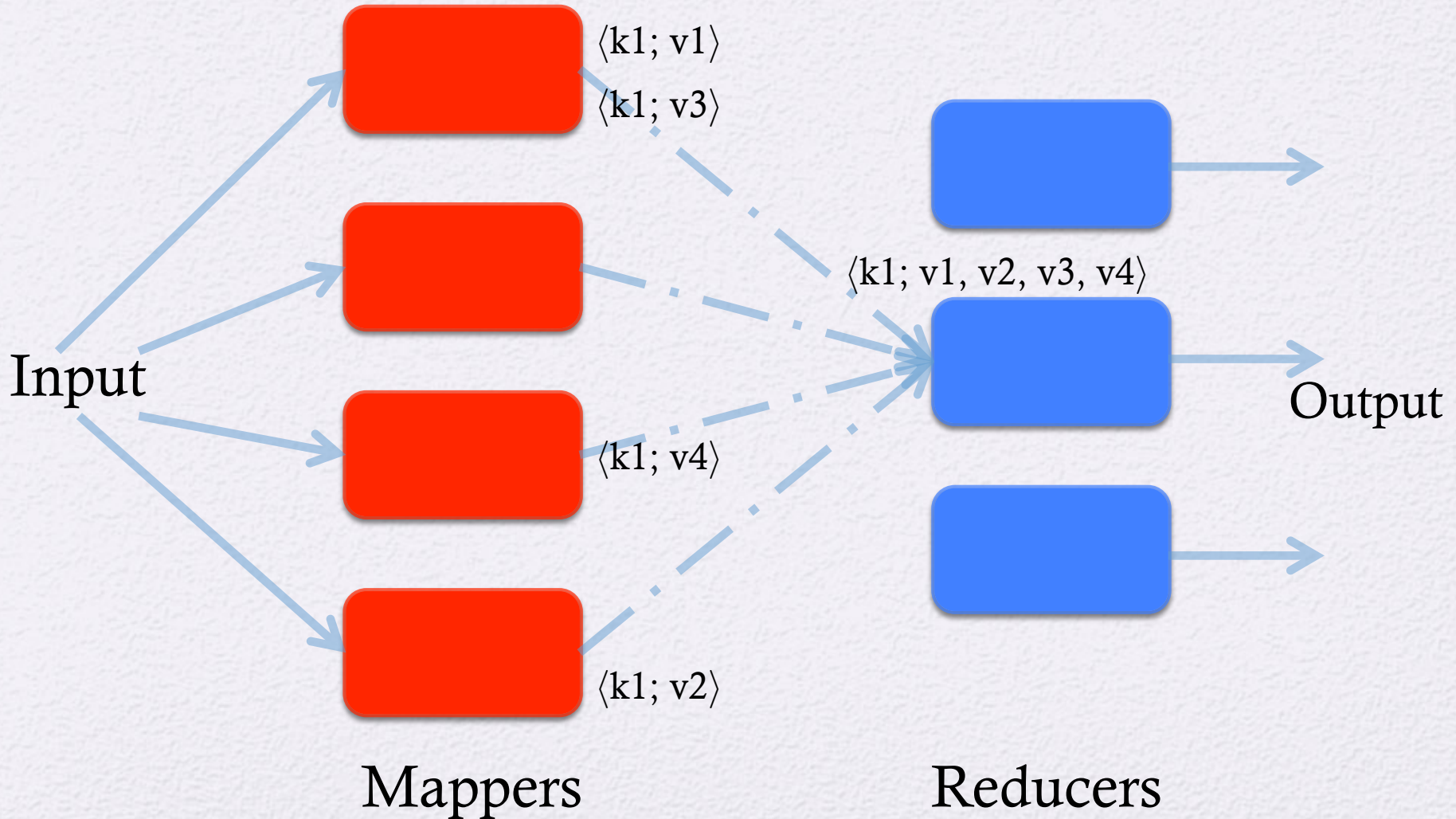
Each reducer processes all pairs with the **same key**

Internal **shuffle** phase ensures this

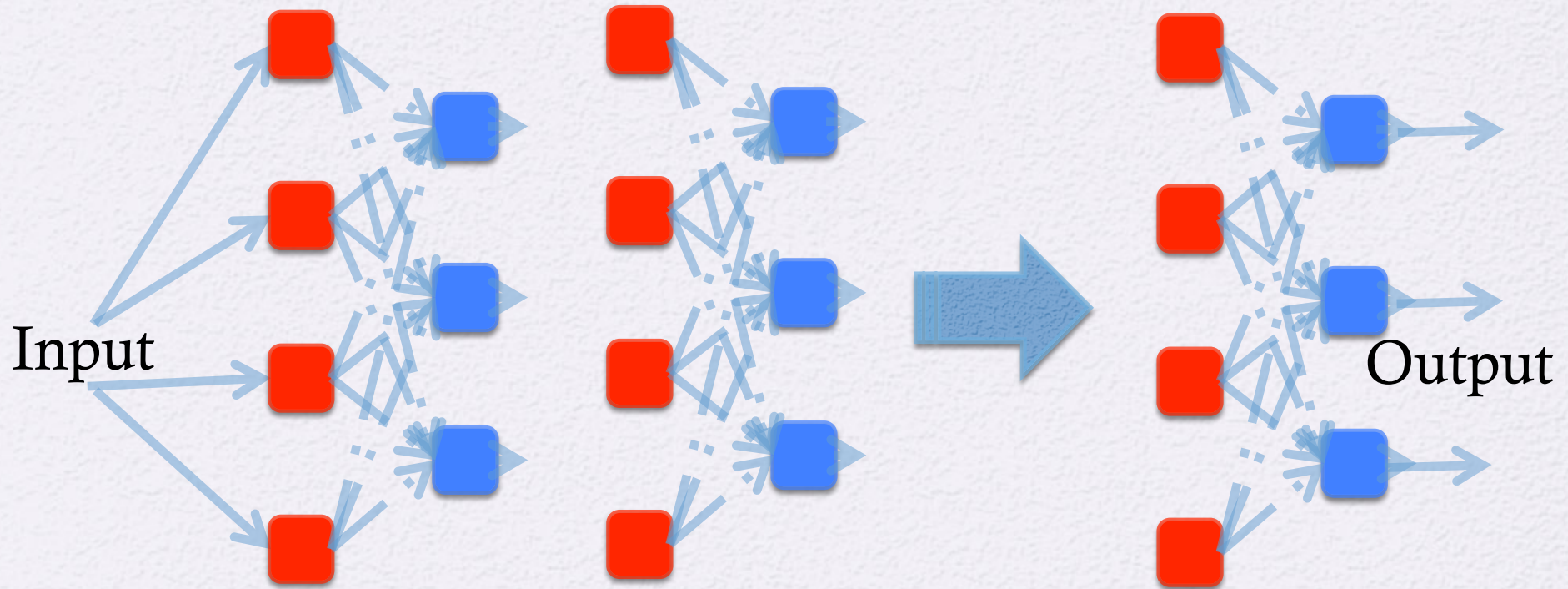
# MR model (contd)



# MR model: Example



# Multi-round MR



# Modeling MR

- Input size =  $n$
- Memory
  - Cannot store the data in memory
  - Use **sublinear memory** per machine:  $n^{1-\epsilon}$  for some  $\epsilon > 0$
- Machines
  - Machines do not share memory
  - **Sublinear number of machines**:  $n^{1-\epsilon}$  for some  $\epsilon > 0$
- Synchronization
  - Computation proceeds in **rounds**
  - Goal is to run in a constant number of rounds

# Communication cost

- Very **important**, makes a big difference
- Huge improvements possible by
  - Moving code to data (and not data to code)
  - Working with graphs: save graph structure locally between rounds
  - Job scheduling (eg, same vs different racks)
- **Minimizing communication** always a goal

# MR Warmup: Tranpose

Given a sparse term-document matrix  $A = [A_{ij}]$  in a row-major order, output  $A$  in column-major order

<b>a</b>	<b>b</b>	
	<b>c</b>	<b>d</b>
	<b>e</b>	

1; 1:a, 2:b  
2; 2:c, 3:d  

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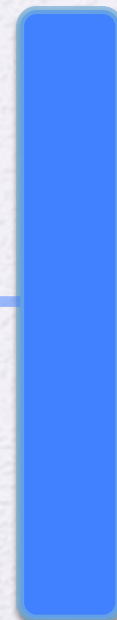
3; 2:e



1; 1:a  
2; 1:b  
2; 2:c  
3; 2:d  
2; 3:e

...  
s  
h  
u  
f  
f  
l  
e  
...

2; 1:b  
2; 3:e  
2; 2:c  
3; 2:d  
1; 1:a



1; 1:a  
2; 1:b, 2:c, 3:e  
3; 2:d

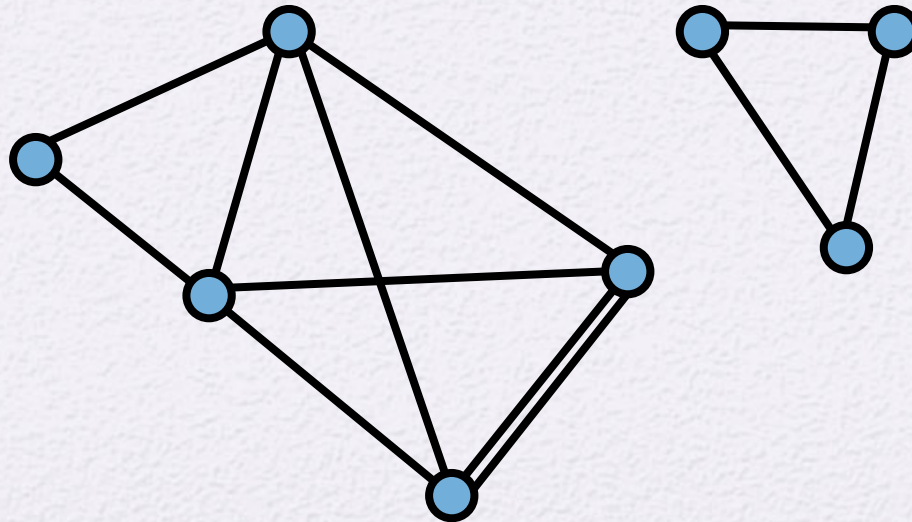
# MR Algorithmic philosophy

- Find the **core** of the problem
- **Partition** the input across mappers
- Solve the problem on partitioned inputs on each mapper and emit the **partial solutions**
- **Tools** at disposal
  - Sampling
  - Filtering redundant information
  - Sketching
  - Careful partitioning to mitigate skew
- Reducer **combines** the individual solutions

# Connected components

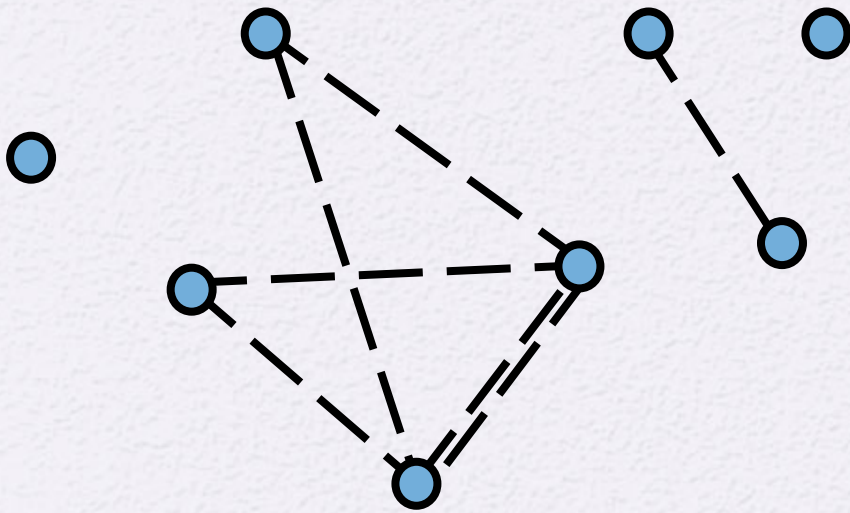
Given an undirected graph, find the connected components

Motivation: Basic question

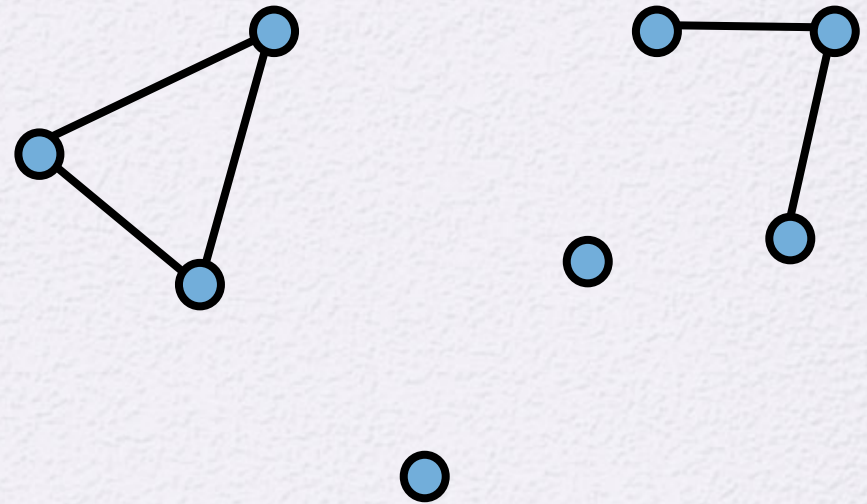


# CC: Algorithm

Partition the edges randomly



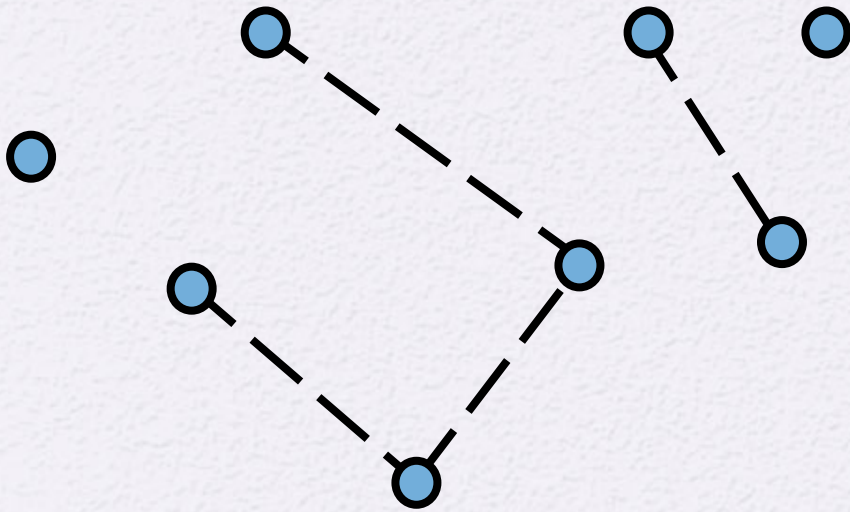
Mapper 1



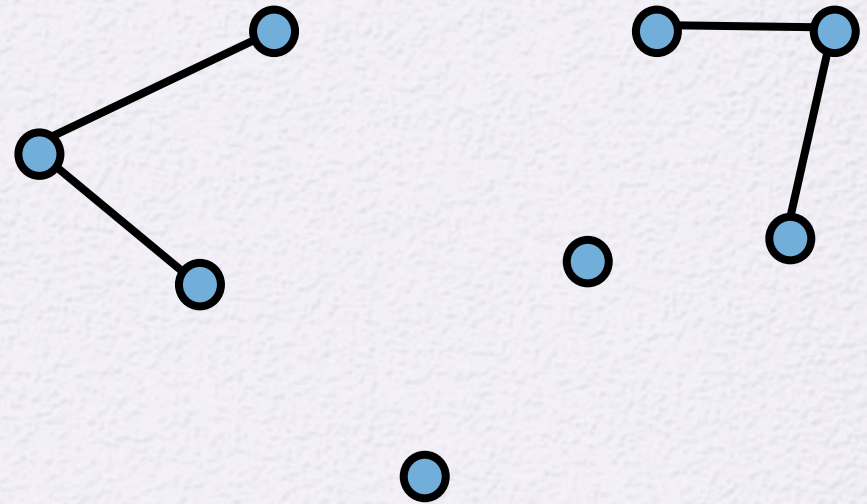
Mapper 2

# CC Algorithm (contd)

Each mapper finds CC on its input



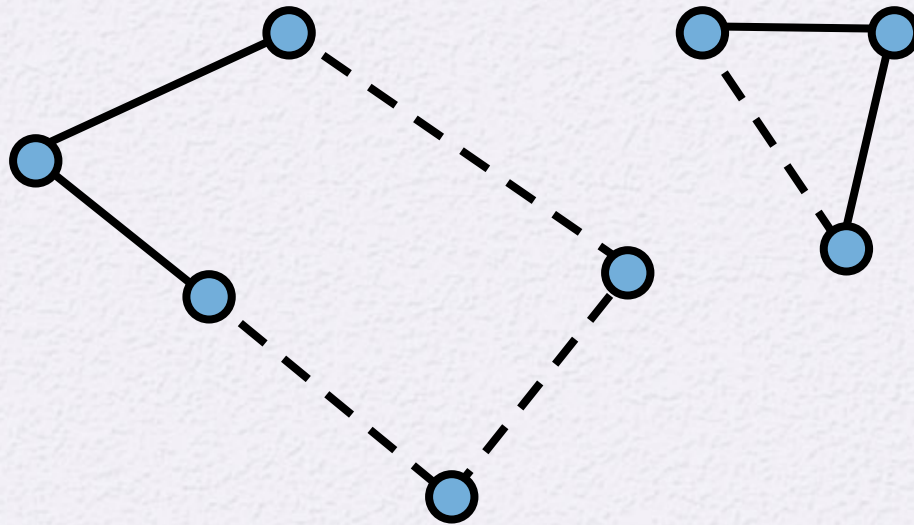
Mapper 1



Mapper 2

# CC Algorithm (contd)

**Reducer combines edges and computes CC**



# CC Analysis

$n$  = number of nodes,  $m$  = number of edges

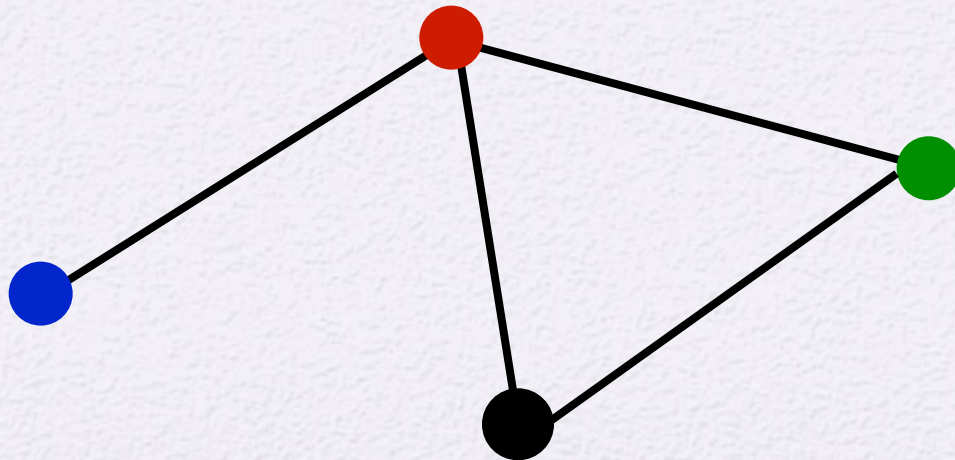
If we have  $k$  mappers

- Total **time** =  $T_{cc}(m/k + n) + T_{cc}(nk)$
- Total **memory** per machine =  $O(n)$ 
  - Since we can stream through the edges
- **Number of rounds** = 2
- Works well for graphs where the number of edges is super-linear in the number of nodes

# Triangle counting

Given an undirected graph, count the number of triangles

Motivation: Social network analysis



# Naïve algorithm

Sequential algorithm

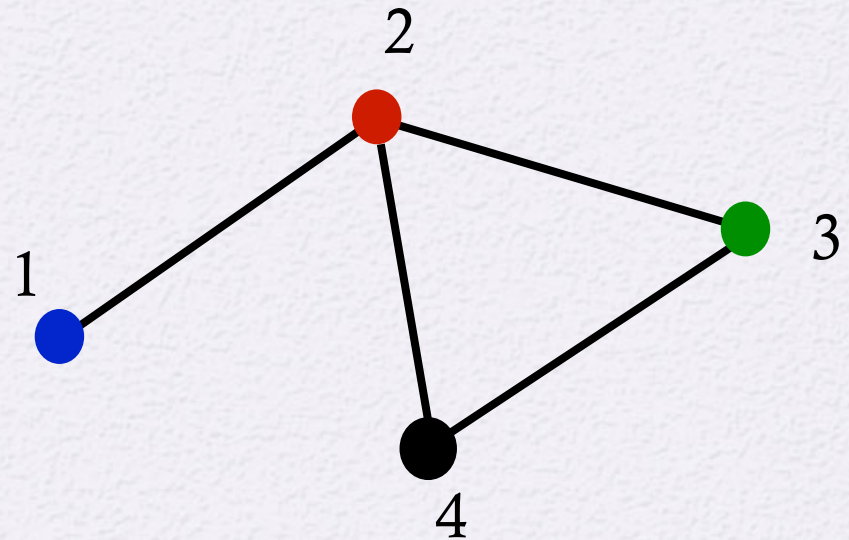
for  $u \in V$ :

for  $(v, w) \in N(u)$ :

if  $(v, w) \in E$ :

**triangles[u]++**

Running time:  $\sum_v \deg(v)^2$



# Naïve algorithm in MR

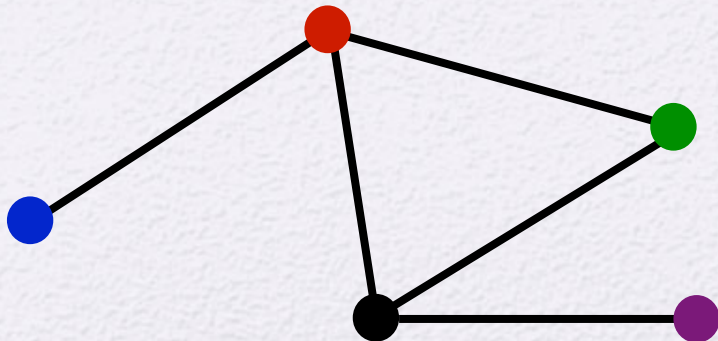
Generate all length-two paths and check if there is an edge linking the end nodes

Map1

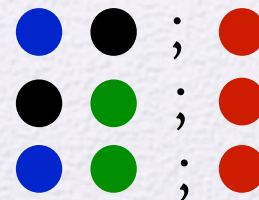
Input:  $(u, v) \in E$   
Emit:  $\langle u; v \rangle$

Reduce1

Input:  $\langle u; N(u) \rangle$   
Output:  $\langle (v, w); u \rangle$   
for  $(v, w) \in N(u)$



A path from v to w goes through u



# Naïve algorithm (contd)

Map2

Input:  $(u, v) \in E$  and

$\langle (v, w); u \rangle$

Emit:  $\langle (u, v); \$ \rangle$

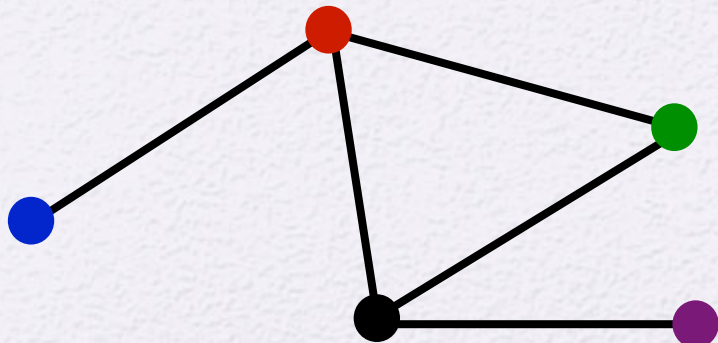
$\langle (v, w); u \rangle$

Reduce2

Input:  $\langle (v, w); u_1, u_2, \dots, u_k, \$? \rangle$

Output: If \$ is present, then  
 $\text{triangle}[u_i] += 1/3$

\$ confirms the existence of  $(v, w)$  edge



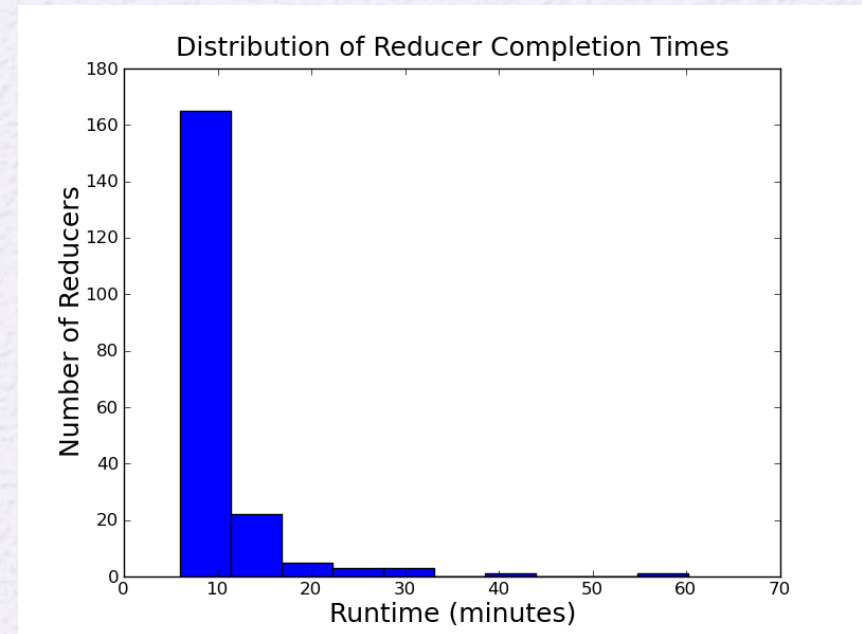
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# Naïve algorithm: Scalability

Does this **scale**?

- Best parallel running time:  $\max_v \deg(v)^2$
- If maximum degree is high (eg, Twitter follower graph), then the algorithm is **slow** even with maximum parallelism

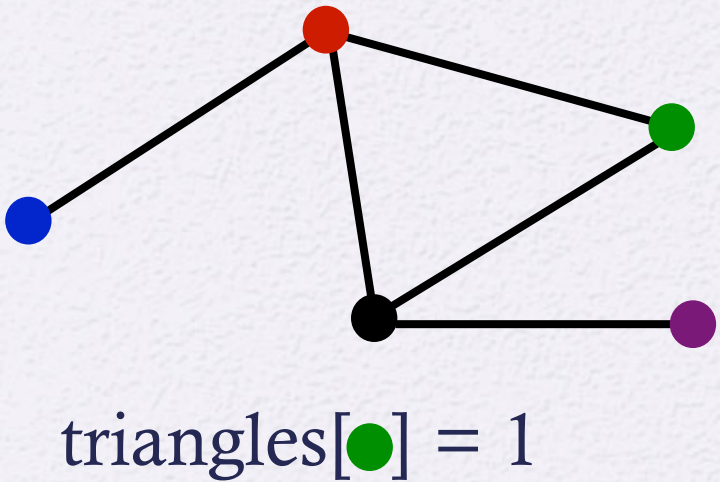


# Improved algorithm

Two ideas:

- Count each triangle once from the point of view of the **lowest degree node in the triangle**
  - for  $u \in V$ :**
    - for  $(v,w) \in N(u)$ :**
      - if  $\text{deg}(u) \leq \min(\text{deg}(v), \text{deg}(w))$** 
        - if  $(v,w) \in E$ :**
          - $\text{triangles}[u]++$**
- **Divide** the graph into overlapping subgraphs across mappers

# Improved algorithm: Analysis



**Theorem.** Total work =  $O(m^{3/2})$

**Proof.**  $L = \{ u : \deg(u) \leq \sqrt{m} \}$

$H = \{ u : \deg(u) > \sqrt{m} \}; |H| \leq \sqrt{m}$

Nodes in  $H$  produce paths for **at most  $|H|^2$  neighbor pairs**  $\Rightarrow$   
 $O(m^{3/2})$  paths

$m_i$  = total number of edges adjacent to nodes of degree  $d_i$ ;  $\sum m_i = 2m$ ;  $m_i \leq m/i$

Nodes in  $L$  produce  $\sum_{u \in L} \deg(u)^2 p = \sum_i i^2 m_i / i = O(m^{3/2})$  paths

# Improved algorithm: tradeoff

Time vs memory **tradeoff**

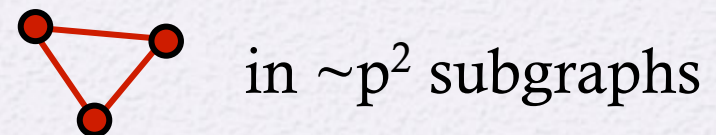
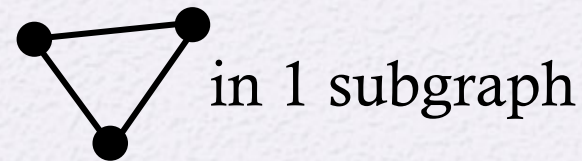
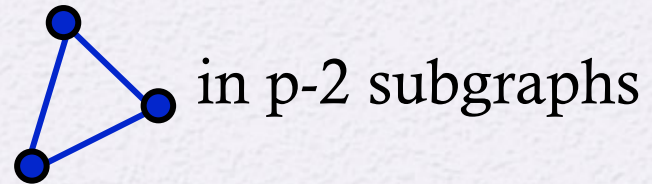
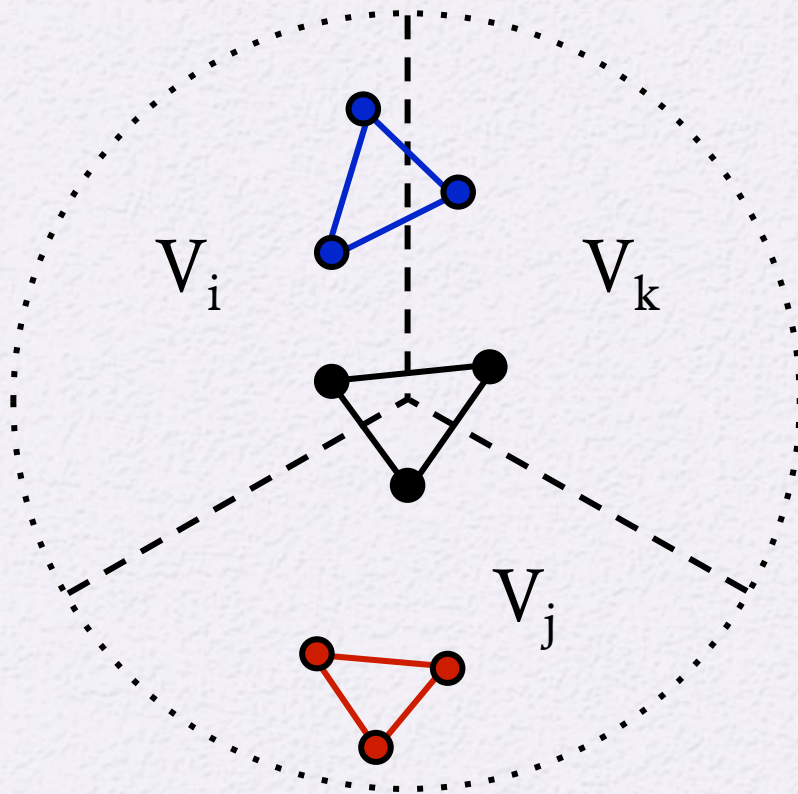
**Partition** nodes into equal-sized  $V_1, \dots, V_p$

Consider all possible **triples**  $\langle V_i, V_j, V_k \rangle$  and the induced subgraph  $G_{ijk}$

Count triangles in each  $G_{ijk}$  in **parallel**

Carefully track **overcounting**

# Tradeoff (contd)



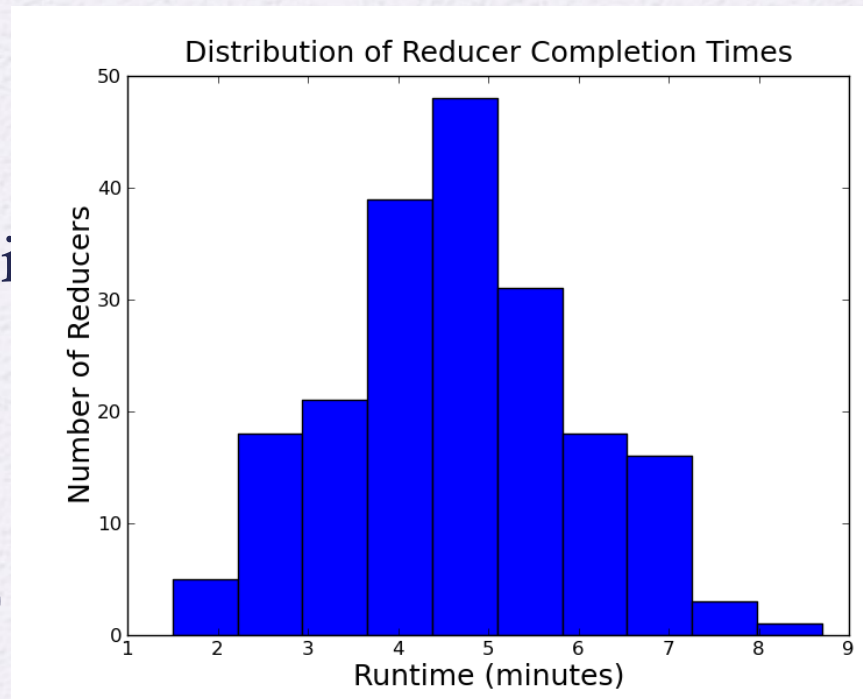
Can count **exactly** how many subgraphs each triangle will be in

# Improved algorithm: Scalability

- **Balanced** running times
- Parameter  $p$  controls memory per machine
- Number of edges per partition is  $\sim m/p^2$
- Total work

$$p^3 O((m/p^2))^{3/2} = O(m^{3/2})$$

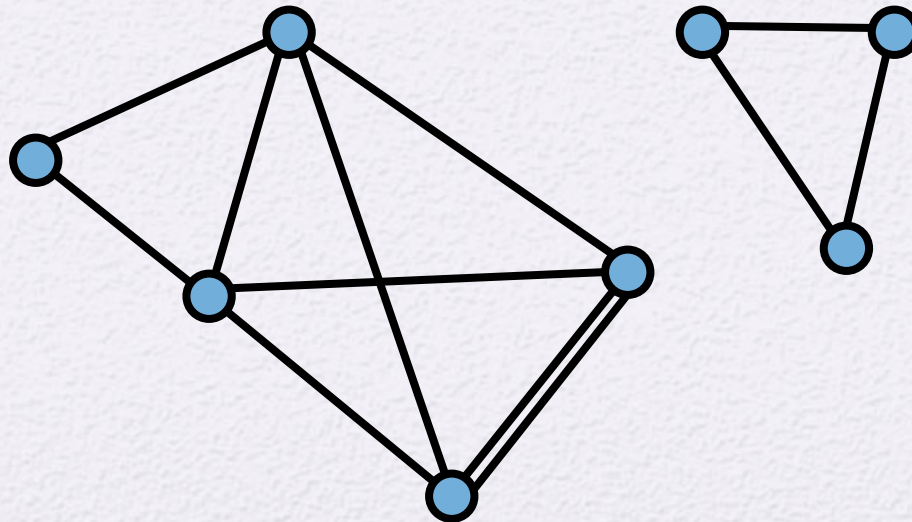
- **Lesson:** Treat data skew carefully



# Maximal matching

Given an undirected graph, finding a maximal matching

Motivation: Matching advertiser and content

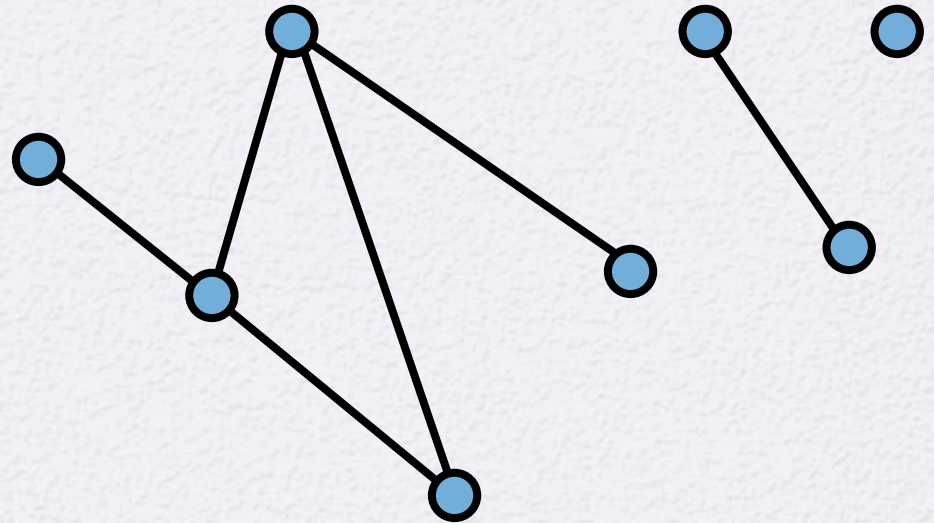


# Max. matching (contd)

- First idea
  - **Randomly** partition the nodes across machines
  - Find a matching on each partition
  - Compute a matching on the matchings
  - **Does not work: can make very slow progress**
- A **better** idea
  - Find a seed matching on a **sample**
  - **Prune all dead edges**
    - Edge dead if an endpoint already matched
  - **Recurse** on remaining edges

# MM: Algorithm

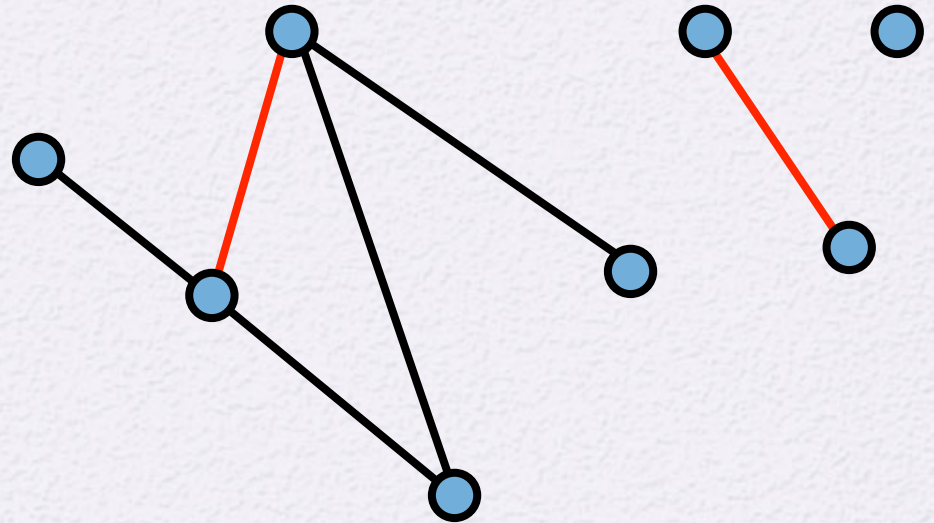
**Sample edges  
uniformly at  
random**



# MM Algorithm (contd)

**Sample edges  
uniformly at  
random**

**Find a maximal  
matching on the  
sample**

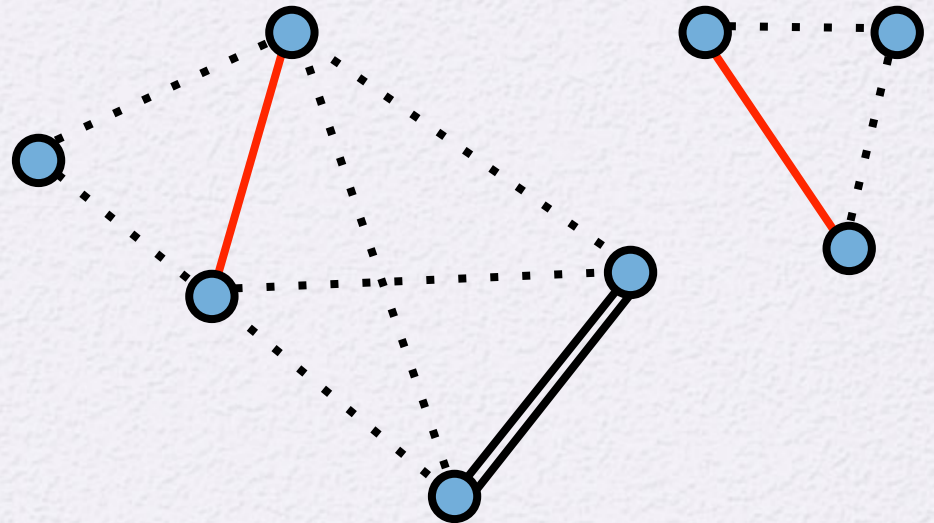


# MM Algorithm (contd)

**Sample edges  
uniformly at  
random**

**Find a maximal  
matching on the  
sample**

**Look at the  
original graph,  
prune dead edges**



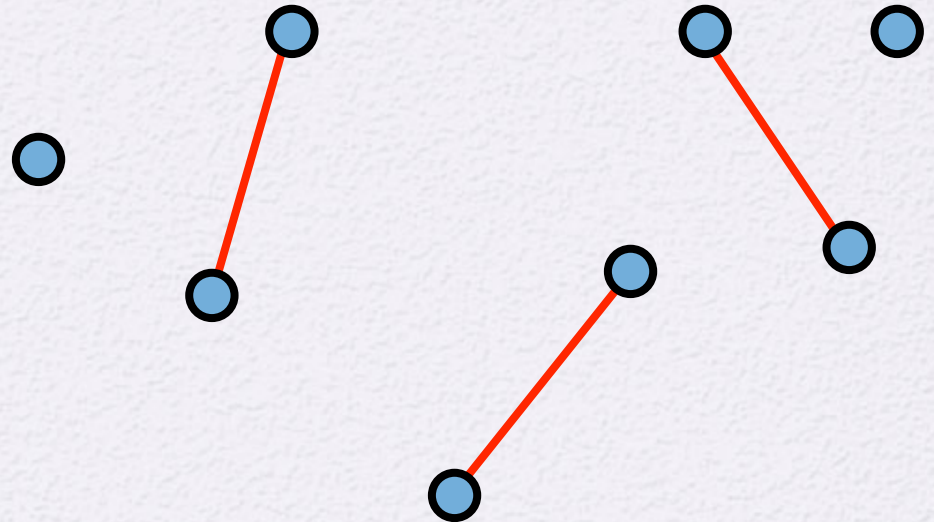
# MM Algorithm (contd)

**Sample edges uniformly at random**

**Find a maximal matching on the sample**

**Look at the original graph, drop dead edges**

**Find maximal matching on the remaining edges**



# MM: Analysis

**Lemma.** Let the sampling rate  $p = n^{1+c}/m$  for some  $c > 0$ . Then, whp, the number of **edges left after the prune** step is at most  $2n/p = 2m/n^c$

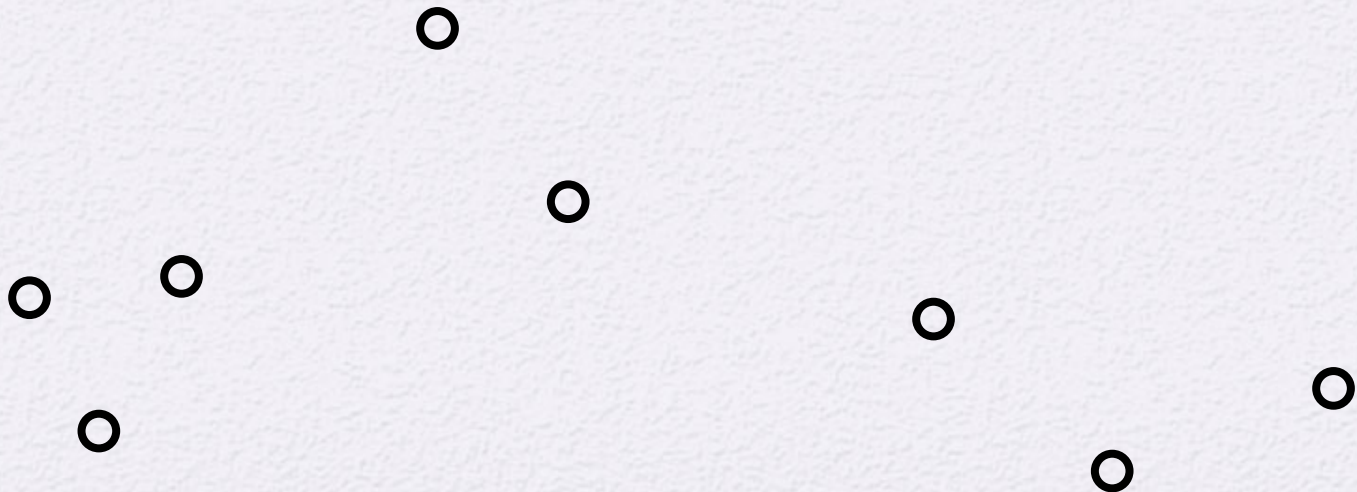
**Proof.** Suppose  $J$  is unmatched after the prune step  $\Rightarrow J$  was an independent in the sampled graph. If  $|E[J]| > O(n/p)$ , then it is an independent set with probability at most  $\exp(-n)$ . Take a union bound over all subsets  $J$ .

**Corollary.** With  $O(n^{1+c})$  memory, the algorithm runs in  $O(1)$  rounds; with  $O(n \log n)$  memory, the algorithms runs in  $O(\log n)$  rounds

# K-means

Given a set of points and  $k > 0$ , partition the points into  $k$  clusters to minimize sum of squares error

Motivation: Fundamental clustering primitive



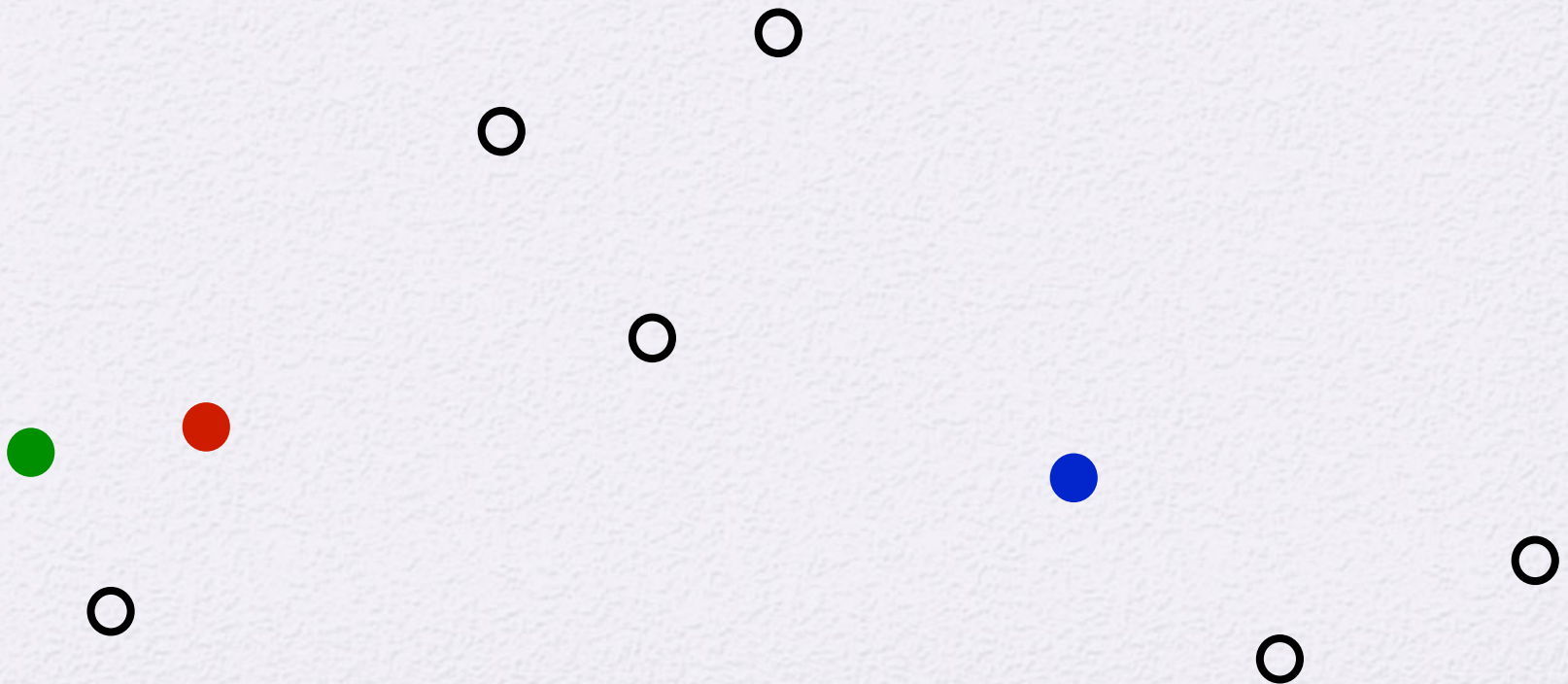
# K-means: Algorithm

Lloyd's method

- **Randomly pick k centers**
- **Repeat until clustering does not change**
  - **Assign each point to its nearest center**
  - **Recompute centers of each cluster**

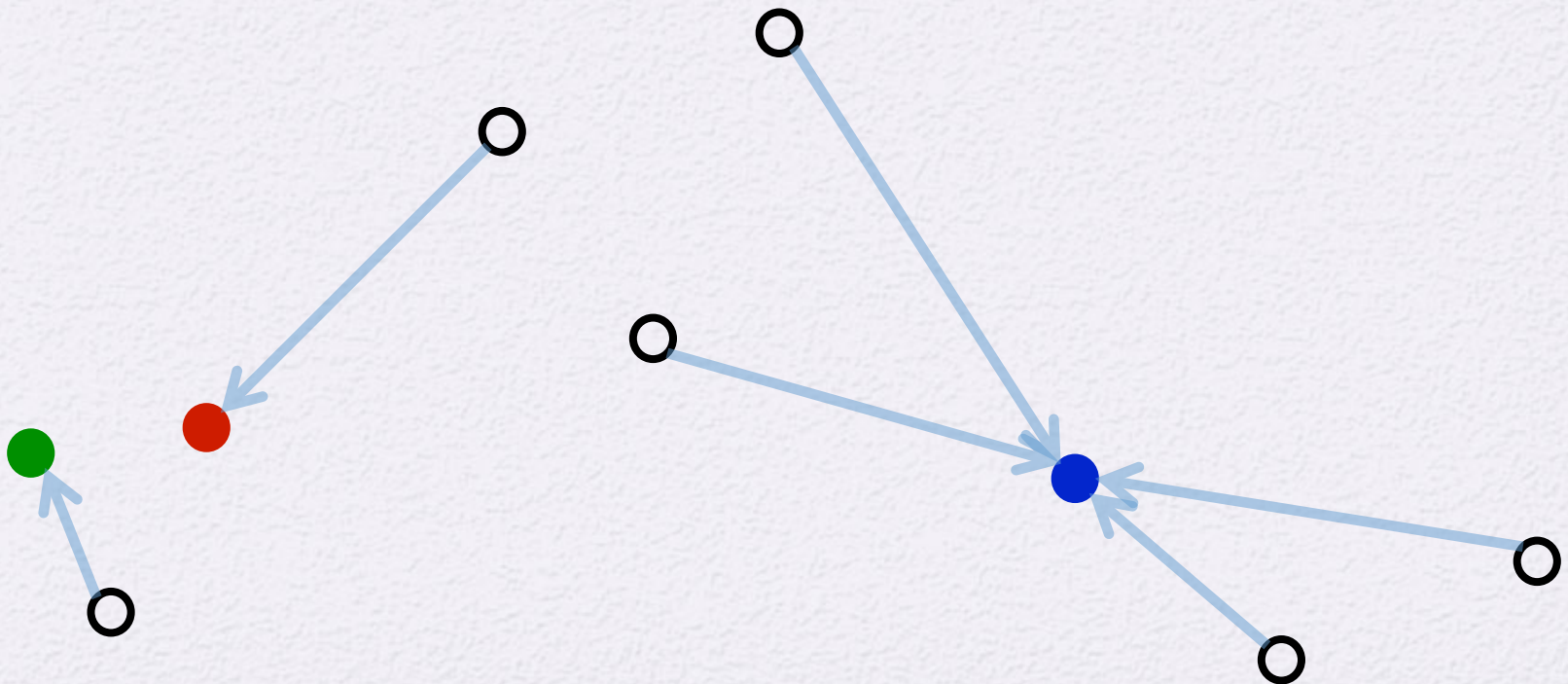
# Lloyd's method: Example

- $k = 3$ ; pick 3 random centers



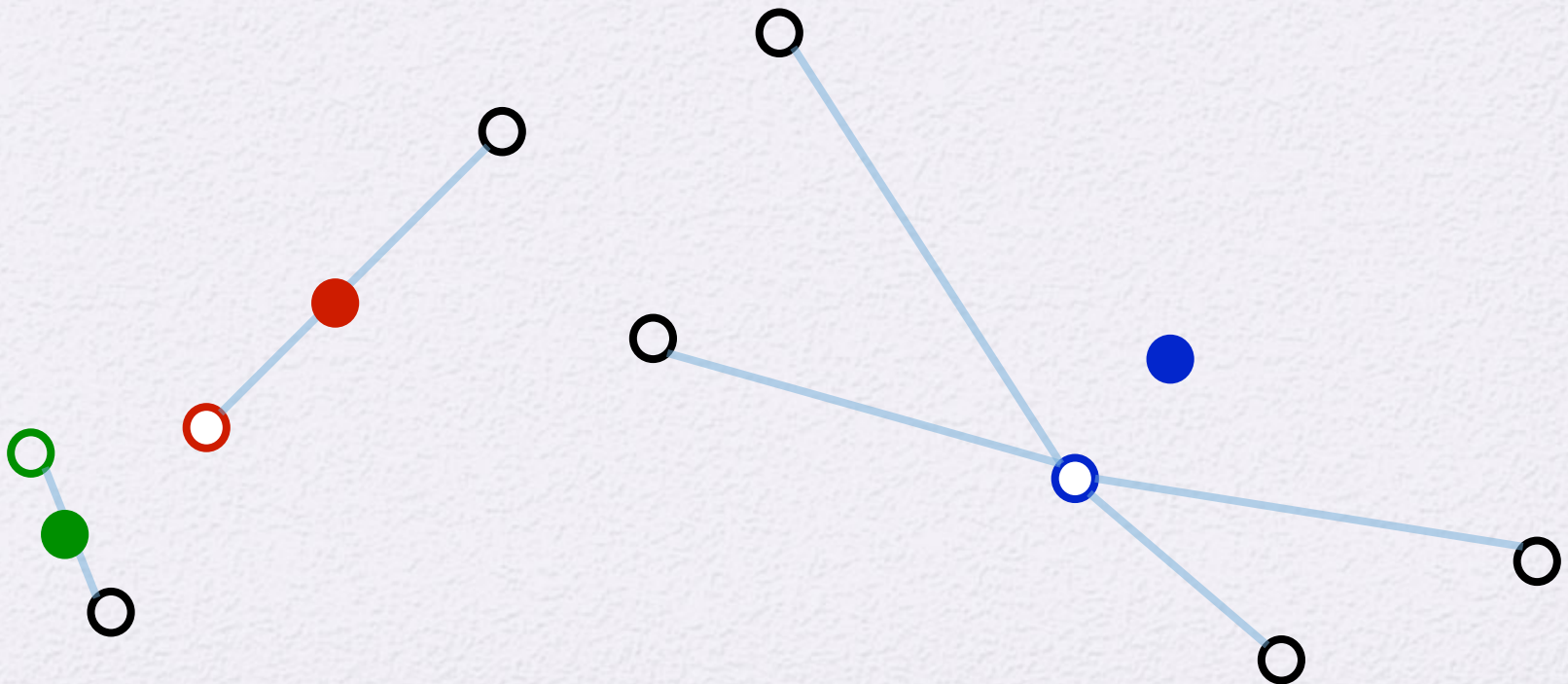
# Lloyd's method (contd)

- Assign each point to its nearest center



# Lloyd's method (contd)

- Recompute centers



# K-means++

**K-means++:** Instead of random initial centers, choose more carefully

- $D(p)$  = distance of  $p$  to a closest center

Choose next cluster center  $\propto D^2(p)$

- Give **preference** to points that are far away from existing centers
- Inherently **sequential** algorithm

**Theorem.** K-means++ is an  $O(\log k)$  approximation

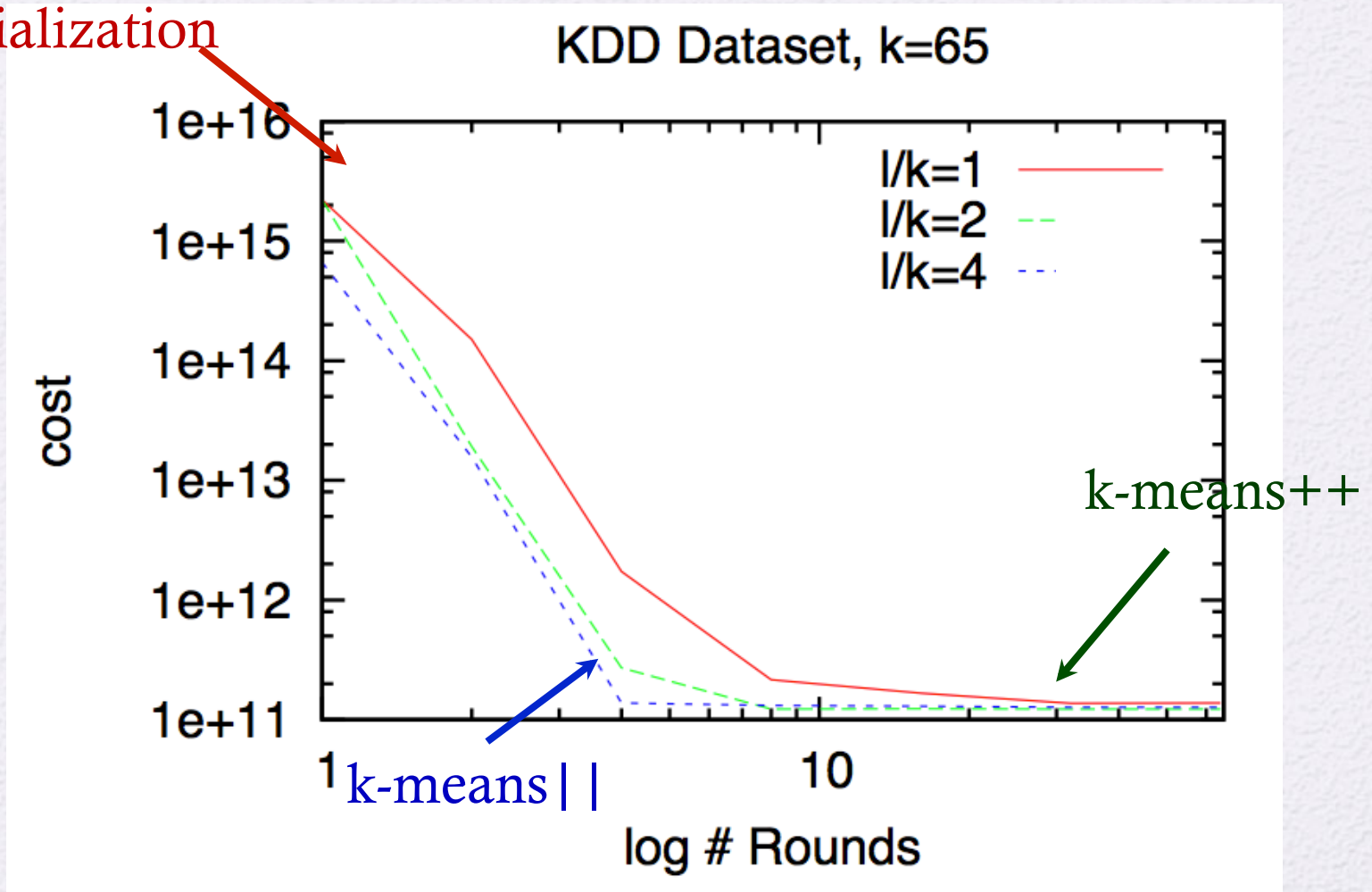
# K-means | |

- How to adapt K-means++ to MapReduce?
- Use **sample and prune** method
  - **Independently (over)sample  $k * L$  points in each round**
  - **Prune back to  $k$  points by reclustering**

**Theorem.** After  $\log_L$  rounds, we get  $O(1)$ -approximation

# K-means | | : Performance

Random  
Initialization



# MR: Some references

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- H. Karloff, S. Suri, S. Vassilvitskii. A model of computation for MapReduce. SODA 2010
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*Xie Xie!*

Questions/Comments

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